

# 100-tap Digital **Potentiometer (POT)**

# **CAT5113**

#### Description

The CAT5113 is a single digital POT designed as an electronic replacement for mechanical potentiometers. Ideal for automated adjustments on high volume production lines, they are also well suited for applications where equipment requiring periodic adjustment is either difficult to access or located in a hazardous or remote environment.

The CAT5113 contains a 100-tap series resistor array connected between two terminals R<sub>H</sub> and R<sub>L</sub>. An up/down counter and decoder that are controlled by three input pins, determines which tap is connected to the wiper, Rw. The wiper setting, stored in nonvolatile memory, is not lost when the device is powered down and is automatically reinstated when power is returned. The wiper can be adjusted to test new system values without affecting the stored setting. Wiper-control of the CAT5113 is accomplished with three input control pins,  $\overline{CS}$ ,  $U/\overline{D}$ , and  $\overline{INC}$ . The  $\overline{INC}$  input increments the wiper in the direction which is determined by the logic state of the  $U/\overline{D}$  input. The  $\overline{CS}$  input is used to select the device and also store the wiper position prior to power down.

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100-position Linear Taper Potentiometer
Non-volatile EEPROM Wiper Storage
10 nA Ultra-low Standby Current
Single Supply Operation: 2.5 V – 6.0 V
Increment Up/Down Serial Interface
Resistance Values: 1 kO 10 10 The digital POT can be used as a three-terminal resistive divider or

- Available in PDIP, SOIC, TSSOP and MSOP Packages
- These Devices are Pb-Free, Halogen Free/BFR Free and are RoHS Compliant

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#### **Applications**

- Automated Product Calibration
- Remote Control Adjustments
- Offset, Gain and Zero Control
- Tamper-proof Calibrations
- Contrast, Brightness and Volume Controls
- Motor Controls and Feedback Systems
- Programmable Analog Functions



**V SUFFIX** CASE 751BD



**Z SUFFIX** CASE 846AD

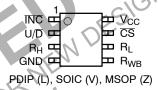


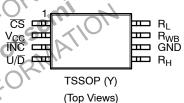
**L SUFFIX** CASE 646AA



Y SUFFIX CASE 948AL

#### PIN CONFIGURATIONS





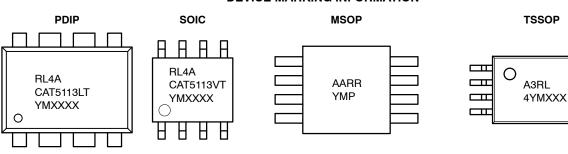
#### **PIN FUNCTION**

Pin Name	Function	
ĪNC	Increment Control	
U/D	Up/Down Control	
R <sub>H</sub>	Potentiometer High Terminal	
GND	Ground	
R <sub>W</sub>	Wiper Terminal	
$R_{L}$	Potentiometer Low Terminal	
CS	Chip Select	
V <sub>CC</sub>	Supply Voltage	

## **ORDERING INFORMATION**

See detailed ordering and shipping information in the package dimensions section on page 9 of this data sheet.

#### **DEVICE MARKING INFORMATION**



R = Resistance:

 $0 = 1 k\Omega$ 

 $2 = 10 \text{ k}\Omega$ 

 $4 = 50 \text{ k}\Omega$ 

 $5 = 100 \text{ k}\Omega$ 

L = Assembly Location

4 = Lead Finish - NiPdAu

A = Product Revision (Fixed as "A")

CAT5113L = Device Code (PDIP)

CAT5113V = Device Code (SOIC)

Assemb.

Ass

ABCN = CAT5113ZI-01-T3

AARR = CAT5113ZI-10-T3

AARC = CAT5113ZI-50-T3

AARG = CAT5113ZI-00-T3

Y = Production Year (Last Digit)

M = Production Month (1-9, A, B, C)

P = Product Revision

A3 = Device Code

R = Resistance:

 $0 = 1 k\Omega$ 

 $2 = 10 \text{ k}\Omega$ 

 $4 = 50 \text{ k}\Omega$ 

 $5 = 100 \text{ k}\Omega$ 

L = Assembly Location

4 = Lead Finish - NiPdAu

Y = Production Year (Last Digit)

M = Production Month (1-9, A, B, C)

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XXX = Last Three Digits of

Assembly Lot Number

#### **Functional Diagram**

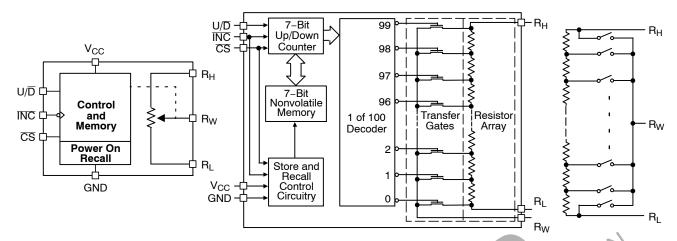


Figure 1. General

Figure 2. Detailed

Figure 3. Electronic Potentiometer Implementation

# **Pin Description**

**INC:** Increment Control Input

The  $\overline{INC}$  input moves the wiper in the up or down direction determined by the condition of the  $U/\overline{D}$  input.

U/**D**: Up/Down Control Input

The  $U\overline{D}$  input controls the direction of the wiper movement. When in a high state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment toward the  $R_H$  terminal. When in a low state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment towards the  $R_L$  terminal.

**R**<sub>H</sub>: High End Potentiometer Terminal

 $R_{\rm H}$  is the high end terminal of the potentiometer. It is not required that this terminal be connected to a potential greater than the  $R_{\rm L}$  terminal. Voltage applied to the  $R_{\rm H}$  terminal cannot exceed the supply voltage,  $V_{\rm CC}$  or go below ground, GND.

**Rw:** Wiper Potentiometer Terminal

 $R_W$  is the wiper terminal of the potentiometer. Its position on the resistor array is controlled by the control inputs,  $\overline{INC}$ ,  $U/\overline{D}$  and  $\overline{CS}$ . Voltage applied to the  $R_W$  terminal cannot exceed the supply voltage,  $V_{CC}$  or go below ground, GND.

**R**<sub>L</sub>: Low End Potentiometer Terminal

 $R_{\rm L}$  is the low end terminal of the potentiometer. It is not required that this terminal be connected to a potential less than the  $R_{\rm H}$  terminal. Voltage applied to the  $R_{\rm L}$  terminal cannot exceed the supply voltage,  $V_{\rm CC}$  or go below ground, GND.  $R_{\rm L}$  and  $R_{\rm H}$  are electrically interchangeable.

CS: Chip Select

The chip select input is used to activate the control input of the CAT5113 and is active low. When in a high state, activity on the  $\overline{\text{INC}}$  and  $\text{U/}\overline{\text{D}}$  inputs will not affect or change the position of the wiper.

## **Device Operation**

The CAT5113 operates like a digitally controlled potentiometer with  $R_H$  and  $R_L$  equivalent to the high and low terminals and  $R_W$  equivalent to the mechanical potentiometer's wiper. There are 100 available tap positions including the resistor end points,  $R_H$  and  $R_L$ . There are 99 resistor elements connected in series between the  $R_H$  and  $R_L$  terminals. The wiper terminal is connected to one of the 100 taps and controlled by three inputs,  $\overline{INC}$ ,  $U/\overline{D}$  and  $\overline{CS}$ . These inputs control a seven–bit up/down counter whose output is decoded to select the wiper position. The selected wiper position can be stored in nonvolatile memory using the  $\overline{INC}$  and  $\overline{CS}$  inputs.

With  $\overline{\text{CS}}$  set LOW the CAT5113 is selected and will respond to the U/ $\overline{\text{D}}$  and  $\overline{\text{INC}}$  inputs. HIGH to LOW transitions on  $\overline{\text{INC}}$  will increment or decrement the wiper (depending on the state of the U/ $\overline{\text{D}}$  input and seven-bit counter). The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. The value of the counter is stored in nonvolatile memory whenever  $\overline{\text{CS}}$  transitions HIGH while the  $\overline{\text{INC}}$  input is also HIGH. When the CAT5113 is powered-down, the last stored wiper counter position is maintained in the nonvolatile memory. When power is restored, the contents of the memory are recalled and the counter is set to the value stored

With INC set low, the CAT5113 may be de-selected and powered down without storing the current wiper position in nonvolatile memory. This allows the system to always power up to a preset value stored in nonvolatile memory.

**Table 1. OPERATION MODES** 

INC	CS	U/D	Operation
High to Low	Low	High	Wiper toward H
High to Low	Low	Low	Wiper toward L
High	Low to High	Х	Store Wiper Position
Low	Low to High	Х	No Store, Return to Standby
Х	High	Х	Standby

**Table 2. ABSOLUTE MAXIMUM RATINGS** 

Parameters	Ratings	Units
Supply Voltage V <sub>CC</sub> to GND	-0.5 to +7	V
Inputs CS to GND	-0.5 to V <sub>CC</sub> +0.5	V
INC to GND	-0.5 to V <sub>CC</sub> +0.5	~(Q,^
U/D to GND	-0.5 to V <sub>CC</sub> +0.5	V
H to GND	-0.5 to V <sub>CC</sub> +0.5	V
L to GND	-0.5 to V <sub>CC</sub> +0.5	V
W to GND	−0.5 to V <sub>CC</sub> +0.5	V
Operating Ambient Temperature Commercial ('C' or Blank suffix)	0 to 70	°C
Industrial ('I' suffix)	-40 to +85	°C
Junction Temperature	+150	°C
Storage Temperature	-65 to 150	°C
Lead Soldering (10 s max)	+300	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Table 3. RELIABILITY CHARACTERISTICS

Symbol	Parameter	Test Method	Min	Тур	Max	Units
V <sub>ZAP</sub> (Note 1)	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000			V
I <sub>LTH</sub> (Notes 1, 2)	Latch-Up	JEDEC Standard 17	100			mA
T <sub>DR</sub>	Data Retention	MIL-STD-883, Test Method 1008	100			Years
N <sub>END</sub>	Endurance	MIL-STD-883, Test Method 1003	1,000,000			Stores

This parameter is tested initially and after a design or process change that affects the parameter.
 Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1 V to V<sub>CC</sub> + 1 V

Table 4. DC ELECTRICAL CHARACTERISTICS ( $V_{CC} = +2.5 \text{ V to } +6 \text{ V unless otherwise specified}$ )

Symbol	Parameter	Conditions	Min	Тур	Max	Units
POWER SUPPL	Y		-	-	-	
V <sub>CC</sub>	Operating Voltage Range		2.5	_	6.0	V
I <sub>CC1</sub>	Supply Current (Increment)	V <sub>CC</sub> = 6 V, f = 1 MHz, I <sub>W</sub> = 0	-	-	100	μΑ
		V <sub>CC</sub> = 6 V, f = 250 kHz, I <sub>W</sub> = 0	-	-	50	μΑ
I <sub>CC2</sub>	Supply Current (Write)	Programming, V <sub>CC</sub> = 6 V	-	-	1000	μΑ
		V <sub>CC</sub> = 3 V	_	-	500	μΑ
I <sub>SB1</sub> (Note 3)	Supply Current (Standby)	$\overline{\text{CS}} = \text{V}_{\text{CC}} - 0.3 \text{ V}$ U/ $\overline{\text{D}}$ , $\overline{\text{INC}} = \text{V}_{\text{CC}} - 0.3 \text{ V}$ or GND	=	0.01	1	μΑ
LOGIC INPUTS						
I <sub>IH</sub>	Input Leakage Current	$V_{IN} = V_{CC}$	=	-	10	μΑ
I <sub>IL</sub>	Input Leakage Current	V <sub>IN</sub> = 0 V	-	-	-10	μΑ
V <sub>IH2</sub>	CMOS High Level Input Voltage	2.5 V ≤ V <sub>CC</sub> ≤ 6 V	V <sub>CC</sub> x 0.7		V <sub>CC</sub> + 0.3	<b>V</b>
$V_{IL2}$	CMOS Low Level Input Voltage		-0.3		V <sub>CC</sub> x 0.2	V
POTENTIOMET	ER CHARACTERISTICS				)~	
R <sub>POT</sub>	Potentiometer Resistance	-01 Device		1		kΩ
		-10 Device	2	10		
		-50 Device	50°	50	7	
		-00 Device	1,250,	100		
	Pot. Resistance Tolerance	105	0, 1	7,	±20	%
$V_{RH}$	Voltage on R <sub>H</sub> pin	WE OUT	0		V <sub>CC</sub>	V
$V_{RL}$	Voltage on R <sub>L</sub> pin	Whi. 10 'E	0		V <sub>CC</sub>	V
	Resolution	(CO', C', CR')	•	1		%
INL	Integral Linearity Error	I <sub>W</sub> . ≤ 2 μA		0.5	1	LSB
DNL	Differential Linearity Error	I <sub>W</sub> ≤ 2 μA		0.25	0.5	LSB
R <sub>WI</sub>	Wiper Resistance	V <sub>CC</sub> = 5 V, I <sub>W</sub> = 1 mA			400	Ω
	I IS AS	V <sub>CC</sub> = 2.5 V, I <sub>W</sub> = 1 mA			1000	Ω
I <sub>W</sub>	Wiper Current	(Note 4)	-4.4		4.4	mA
TC <sub>RPOT</sub>	TC of Pot Resistance			300		ppm/°C
TC <sub>RATIO</sub>	Ratiometric TC				20	ppm/°C
V <sub>N</sub>	Noise	100 kHz / 1 kHz		8/24		nV/√Hz
C <sub>H</sub> /C <sub>L</sub> /C <sub>W</sub>	Potentiometer Capacitances			8/8/25		pF
fc	Frequency Response	Passive Attenuator, 10 k $\Omega$		1.7		MHz

<sup>3.</sup> Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1 V to  $V_{CC}$  + 1 V 4. This parameter is not 100% tested.

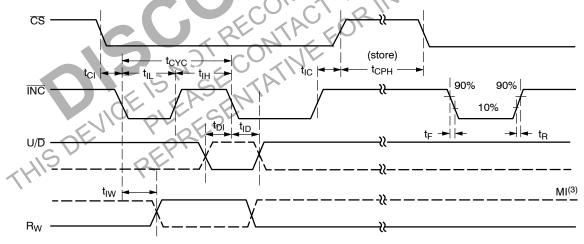
**Table 5. AC TEST CONDITIONS** 

V <sub>CC</sub> Range	$2.5~V \leq V_{CC} \leq 6~V$
Input Pulse Levels	0.2 $V_{CC}$ to 0.7 $V_{CC}$
Input Rise and Fall Times	10 ns
Input Reference Levels	0.5 V <sub>CC</sub>

 $\textbf{Table 6. AC OPERATING CHARACTERISTICS} \ (V_{CC} = +2.5 \ V \ to \ +6.0 \ V, \ V_H = V_{CC}, \ V_L = 0 \ V, \ unless \ otherwise \ specified)$ 

Symbol	Parameter	Min	Typ (Note 5)	Max	Units
t <sub>Cl</sub>	CS to INC Setup	100	-	-	ns
t <sub>DI</sub>	U/D to INC Setup	50	-	=	ns
t <sub>ID</sub>	U/D to INC Hold	100	-	-	ns
t <sub>IL</sub>	INC LOW Period	250	-	-	ns
t <sub>IH</sub>	INC HIGH Period	250	-	=	ns
t <sub>IC</sub>	INC Inactive to CS Inactive	1	-	-	μs
t <sub>CPH</sub>	CS Deselect Time (NO STORE)	100		-15	ns
t <sub>CPH</sub>	CS Deselect Time (STORE)	10	-	10	ms
t <sub>IW</sub>	ĪNC to V <sub>OUT</sub> Change	-	1	<b>N</b> 5	μs
t <sub>CYC</sub>	INC Cycle Time	1	2 1/2	_	μs
t <sub>R</sub> , t <sub>F</sub> (Note 6)	INC Input Rise and Fall Time		> O/	500	μs
t <sub>PU</sub> (Note 6)	Power-up to Wiper Stable		-66/	~101/	ms
t <sub>WR</sub>	Store Cycle	NOE'	5	10	ms

- Typical values are for T<sub>A</sub> = 25°C and nominal supply voltage.
   This parameter is periodically sampled and not 100% tested.
   MI in the A.C. Timing diagram refers to the minimum incremental change in the W output due to a change in the wiper position.



#### **APPLICATIONS INFORMATION**

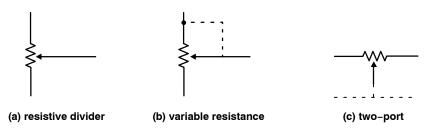


Figure 5. Potentiometer Configuration

# **Applications**

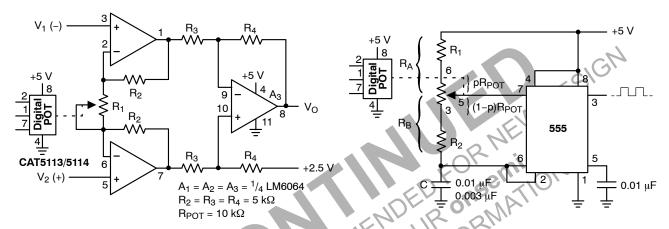


Figure 6. Programmable Instrumentation
Amplifier

Figure 7. Programmable Sq. Wave Oscillator (555)

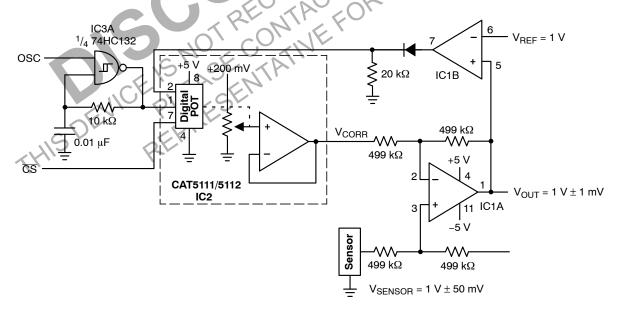


Figure 8. Sensor Auto Referencing Circuit

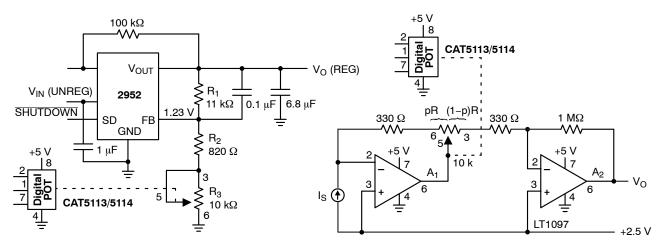


Figure 9. Programmable Voltage Regulator

Figure 10. Programmable I to V Converter

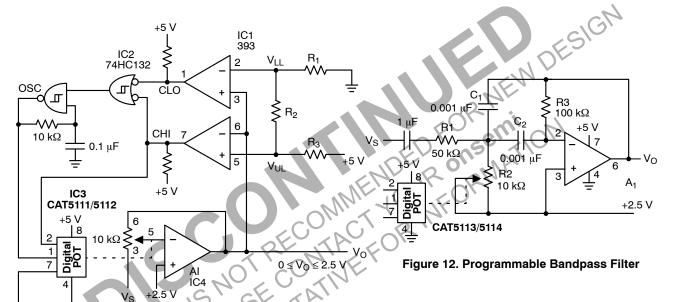


Figure 11. Automatic Gain Control

 $0 \le V_S \le 2.5 \text{ V}$ 

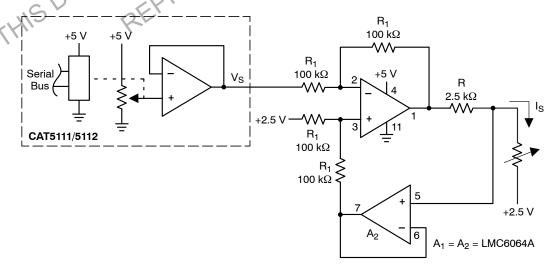


Figure 13. Programmable Current Source/Sink

**Table 7. ORDERING INFORMATION** 

Orderable Part Number	Resistance (k $\Omega$ )	Lead Finish	Package-Pins	Shipping <sup>†</sup>	
CAT5113LI-01-G	1				
CAT5113LI-10-G	10	N:DIA	PDIP-8	50 Helle / Dell	
CAT5113LI-50-G	50	- NiPdAu	(Pb-Free)	50 Units / Rail	
CAT5113LI-00-G	100	1			
CAT5113VI-01-GT3	1				
CAT5113VI-10-GT3	10	N:DIA	SOIC-8	0000 / Table 9 David	
CAT5113VI-50-GT3	50	- NiPdAu	(Pb-Free)	3000 / Tape & Reel	
CAT5113VI-00-GT3	100	1			
CAT5113YI-01-GT3	1				
CAT5113YI-10-GT3	10	N:DIA	TSSOP-8	0000 / Table 9 Deal	
CAT5113YI-50-GT3	50	- NiPdAu	(Pb-Free)	3000 / Tape & Reel	
CAT5113YI-00-GT3	100	1		CIGIL	
CAT5113ZI-01-T3	1			NE S	
CAT5113ZI-10-T3	10		MSOP-8	0000 / To 1 0 Deal	
CAT5113ZI-50-T3	50	- Matte-Tin	(Pb-Free)	3000 / Tape & Reel	
CAT5113ZI-00-T3	100		OR!		

CAT5113ZI-00-T3

100

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

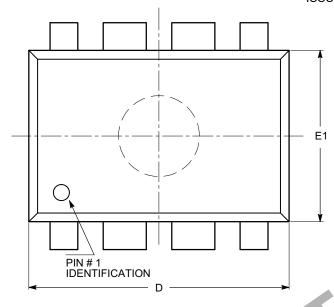
8. All packages are RoHS-compliant (Pb-Free, Halogen-Free).

9. The standard lead finish is NiPdAu, except MSOP package is Matte-Tin.

10. Contact factory for Matte-Tin finish availability for PDIP, SOIC and TSSOP packages.

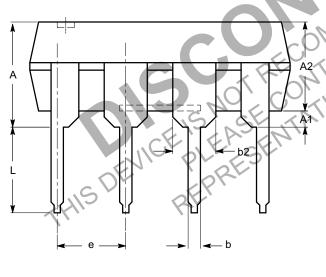
# **PACKAGE DIMENSIONS**

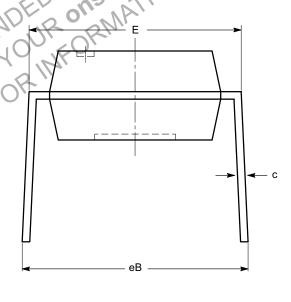
PDIP-8, 300 mils CASE 646AA ISSUE A



SYMBOL	MIN	NOM	MAX
Α			5.33
A1	0.38		
A2	2.92	3.30	4.95
b	0.36	0.46	0.56
b2	1.14	1.52	1.78
С	0.20	0.25	0.36
D	9.02	9.27	10.16
Е	7.62	7.87	8.25
E1	6.10	6.35	7.11
е		2.54 BSC	
eB	7.87	17	10.92
	2.92	3.30	3.80







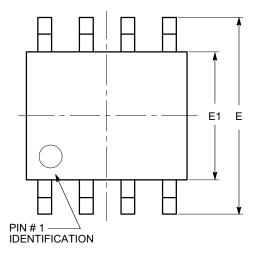
SIDE VIEW END VIEW

#### Notes:

- (1) All dimensions are in millimeters.
- (2) Complies with JEDEC MS-001.

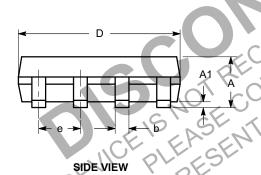
#### **PACKAGE DIMENSIONS**

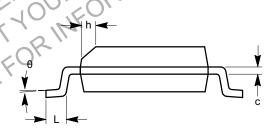
# SOIC 8, 150 mils CASE 751BD ISSUE O



SYMBOL	MIN	NOM	MAX
А	1.35		1.75
A1	0.10		0.25
b	0.33		0.51
С	0.19		0.25
D	4.80		5.00
Е	5.80		6.20
E1	3.80		4.00
е		1.27 BSC	CP.
h	0.25		0.50
L	0.40	100	1.27
θ	0°	N	8°

**TOP VIEW** 



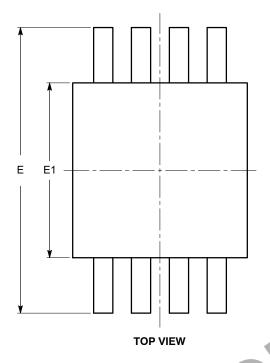


**END VIEW** 

- (1) All dimensions are in millimeters. Angles in degrees. (2) Complies with JEDEC MS-012.

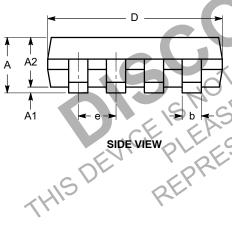
### **PACKAGE DIMENSIONS**

MSOP 8, 3x3 CASE 846AD ISSUE O

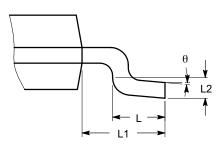


SYMBOL	MIN	NOM	MAX	
Α			1.10	
A1	0.05	0.10	0.15	
A2	0.75	0.85	0.95	
b	0.22		0.38	
С	0.13		0.23	
D	2.90	3.00	3.10	
E	4.80	4.90	5.00	
E1	2.90	3.00	3.10	
е		0.65 BSC	15	
L	0.40	0.60	0.80	
L1	0.95 REF			
L2	0.25 BSC			
θ	0°	mi -	<b>6</b> °	

**DETAIL A** 



# **END VIEW**



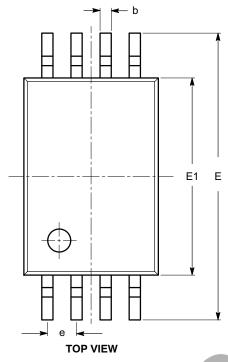
**DETAIL A** 

#### Notes:

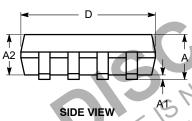
- (1) All dimensions are in millimeters. Angles in degrees.
- (2) Complies with JEDEC MO-187.

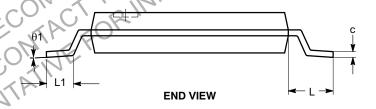
### **PACKAGE DIMENSIONS**

### TSSOP8, 4.4x3 CASE 948AL ISSUE O



SYMBOL	MIN	NOM	MAX	
Α			1.20	
A1	0.05		0.15	
A2	0.80	0.90	1.05	
b	0.19		0.30	
С	0.09		0.20	
D	2.90	3.00	3.10	
Е	6.30	6.40	6.50	
E1	4.30	4.40	4.50	
е		0.65 BSC	1	
L	1.00 REF			
LY	0.50	0.60	0.75	
θ	0%	celli	8°	





#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.(2) Complies with JEDEC MO-153.



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